

Topics in Inverse Problems

**Course summary & projects
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Recap

Part I: Linear Inverse Problems

- Well-posed problems: Hadamard's criteria, examples
- Integral equations (1st kind) in a Hilbert space setting
- Picard's theorem: conditions for solvability of $Ax = y$ when $A : X \rightarrow Y$ is a compact operator
- Regularization: using a-priori information for restoring **stability**
 - (best) a-priori stability estimates
 - “generic” regularisation scheme: “frequency” filters, convergence
 - Tikhonov regularisation
 - A-posteriori parameter selection: L-curve, discrepancy principle
- Discretization: quadrature, collocation, Galerkin
- Iterative methods: Landweber iteration, conjugate gradient

Part II: (Classical) Resolution & Super-resolution

- Nyquist sampling theorem
- Measures of resolution
 - “Highest frequency”: decay of singular values of the forward operator
 - mildly vs severely ill-posed problems
 - Zero-spacings (oscillations) of singular functions
- Bandlimited systems and convolution operators
 - Frequency domain regularisation
 - Distribution of eigenvalues, Szego’s theorems
 - Ideal low-pass kernel (sinc / Slepian operator): singular system
 - SR for space-limited objects: logarithmic improvement in resolution
- Super-resolution and analytic continuation
 - A-priori stability via potential theory
 - General approach via expansions, choosing optimal truncation parameter
 - Paley-Wiener theorem
 - Speed of convergence of the trapezoidal rule

Part III: parametric super-resolution

- Non-smooth problems: linear methods not accurate enough
- Detection of singularities in piecewise-smooth functions: an algebraic method. Optimal dependence on smoothness between jumps.
- Super-resolution of point sources: $f(t) \sim \sum c_j \delta(t - t_j)$ from moments $m_k = \hat{f}(k)$, $k = 0, 1, \dots, N$ and additive bounded noise $\|e\| \leq \epsilon$
 - Existence&uniqueness: Hankel matrices, Pade approximation
 - Local stability: Jacobians, Vandermonde matrices, Hermite interpolation.
 - Decimation: selecting a well-behaved subset of equations
 - Semi-local stability: bound on ϵ . Quantitative inverse function theorem.
 - Dependence of stability on the minimal separation Δ , bandwidth N and clustering
 - Phase transition $N \approx 1/\Delta$
 - Minimax framework: best worst-case error and oracle algorithm
 - Stability of least-squares

 D. Batenkov, G. Goldman, and Y. Yomdin, "Super-resolution of near-colliding point sources," *Arxiv:1904.09186 [math]*, 2019.

  D. Batenkov, "Stability and super-resolution of generalized spike recovery," *Applied and computational harmonic analysis*, vol. 45, iss. 2, pp. 299-323, 2018.

  D. Batenkov, "Complete Algebraic Reconstruction of Piecewise-Smooth Functions from Fourier Data," *Mathematics of Computation*, vol. 84, iss. 295, p. 2329–2350, 2015.

  D. Batenkov and Y. Yomdin, "On the accuracy of solving confluent Prony systems," *SIAM J. Appl. Math.*, vol. 73, iss. 1, p. 134–154, 2013.

Projects

General guidelines

- Groups of 2-3
- Singles are OK but require prior confirmation
- Requirements: final report + code + presentation
- Structure of the report
 - Introduction: general context, motivation
 - Summary of relevant paper (s)
 - Optional chapters (e.g. **your** numerical experiments)
 - Formal references
- Report in English (LaTeX), 10-15 pages, code in any programming language
- Document everything! You are evaluated mainly for the effort (but I have to see some proof)
- Timeline:
 - July 15th: send me an email incl. group members and chosen topic (but note that it is first-come first serve)
 - November 1st: submit final report + code
 - Presentation: schedule a meeting within 1 month of the submission deadline
- **90% of the final grade**

Possibility 1: a particular inverse problem of your choice

- Describe the problem (some physics etc.)
- Formulate as an operator
- Demonstrate ill-posedness/ill-conditioning
- Implement a regularisation scheme with parameter selection
- Use simulated (beware of inverse crime) or real data (if you can get it)
- Study resolution

Possible sources:

- Bertero book Chapter 8: X-ray tomography, emission tomography, inverse diffraction, inverse source, linearised inverse scattering
- Hansen's IRTools: deblurring, inverse diffusion, NMR relaxometry, tomography
- Handbook of math. Methods in imaging book - some chapter from part II
- Geophysics: chapters from parts III-V
- ... (a problem you care about)

Other possibilities

1. Open problems mentioned in class
 - May be a jump-start for M.Sc. thesis
 - Talk to me to decide scope
2. A paper from the list
 - Understand, explain, implement algorithm (should be not too difficult in most cases)
 - Study the (super-) resolution properties of the algorithm, comparing to optimal bounds when possible
3. Suggest a topic