

Lecture 11

- "Minimax" bounds for sparse SR
- Quantitative estimates on the neighb. ($\epsilon \ll 1$)
- Stability of least squares
 - Structural perturbations & extensions
 - Open questions

Next time: overview & add. topics, info re. projects
(November),

Last lecture: online quiz

Optimal SR, "mini-max", "worst-case error".

(local approach \rightarrow "semi-local", "semi-global")

$$P_d \text{ (signal space)} = \left\{ (c, x), c \in \mathbb{C}^d, x \in \mathbb{R}^d \right\} \quad \begin{array}{l} \|\cdot\|_{\infty} \\ \text{component} \\ \text{wise} \end{array}$$

$x_1 \leq x_2 \leq \dots \leq x_d$

Ω : bandlimit

data space: $L_{\infty}([- \Omega, \Omega]) \cap C^0 := \mathcal{S}, \|\cdot\| = \|\cdot\|_{\infty}$.

Will consider compact subsets of P_d , $U \subset P_d$,
Prior information $\left\{ \begin{array}{l} \text{min/max amplitudes} \\ \text{clustering, min. separation} \end{array} \right.$

Algorithm: $\mathcal{A}: \{ \alpha: \mathcal{S} \rightarrow \mathcal{U} \} \quad \mathcal{A}(U, \Omega)$.

Min-max / worst case error:

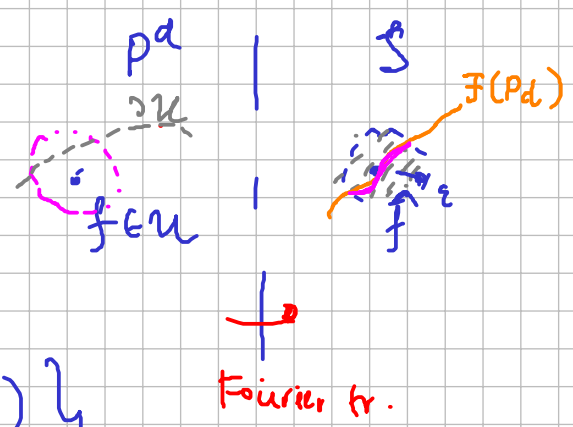
$$j=1, \dots, d: \quad \mathcal{E}_j^{(t_j)} = \mathcal{E}_j^{(t_j)}(U, \varepsilon, \Omega) \quad \left(\mathcal{E}_j^{(c_j)} \right)$$

$$:= \inf_{\alpha \in \mathcal{A}} \sup_{\substack{f \in U \\ c \in \mathcal{S} \\ \|c\| \leq \varepsilon}} \left| t_j - (\alpha(\hat{f} + c))_j^{(t_j)} \right|$$

$f = \sum_{j=1}^d c_j \delta(t - t_j)$

Error sets "preimages"

$$E(f, \epsilon) := \{g \in \mathcal{P}_d : \|\hat{f} - \hat{g}\| \leq \epsilon\}$$



$$E_j^{(\epsilon)} = \left\{ (g)_j^{(\epsilon)} : g \in E(f, \epsilon) \right\}$$

Proposition

$$\frac{1}{2} \sup_{f \in \mathcal{U} \cap E(f, \epsilon)} \text{diam} E_j^{(\epsilon)}(f, \epsilon) \leq C_j^{(\epsilon)}(\mathcal{U}) \leq \sup_{f \in \mathcal{U}} \text{diam} E_j^{(\epsilon)}(f, 2\epsilon)$$

Pf. RHS
"Oracle"

$y \in S$ given

Consider $B(\epsilon, y) = \{f \in \mathcal{U} : \|\hat{f} - y\| \leq \epsilon\}$
(may be \emptyset)

$$d_0 = \begin{cases} g \in B(\epsilon, y) & \text{if } B(\epsilon, y) \neq \emptyset \\ g_0 \in \mathcal{U} & \text{else.} \end{cases}$$

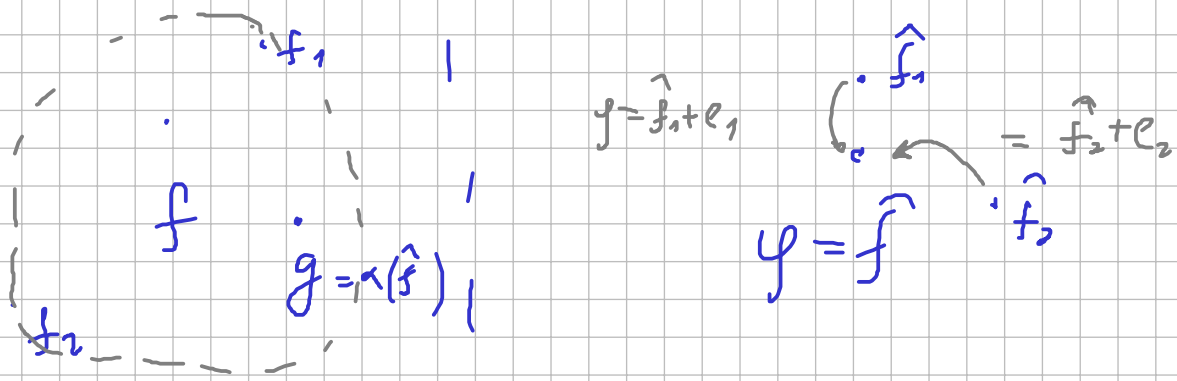
maybe can learn it?

$$f \in \mathcal{U}, \|e\| \leq \epsilon, y = \hat{f} + e \Rightarrow f \in B(\epsilon, y)$$

$$f_0 = d_0(y) \Rightarrow \|\hat{f}_0 - \hat{f}\| \leq 2\epsilon \Rightarrow f_0 \in E(f, 2\epsilon)$$

$$\Rightarrow C_j^{(\epsilon)} \leq \sup_f \text{diam} E_j^{(\epsilon)}(f, 2\epsilon)$$

LHS: $f \in U, \alpha \in \mathcal{A}, g = \alpha(\hat{f})$



$\forall \epsilon > 0$, let's take $f_1, f_2 \in E(f, \epsilon)$,

$$|(f_1)_j^{(w)} - (f_2)_j^{(w)}| \geq \text{diam } E(f, \epsilon) - \epsilon$$

$$\|\hat{f}_1 - g\|, \|\hat{f}_2 - g\| \leq \epsilon$$

So α must make a 'large' error either for f_1 or f_2

$$\epsilon_j^{(w)} = \inf_{\alpha} \sup_{f \in E} |(f)_j^{(w)} - (\alpha(\hat{f}))_j^{(w)}|$$

$$\geq \inf_{\alpha} \max \left\{ |f_1 - g|, |f_2 - g| \right\}$$

\uparrow
proj

$$\geq \inf_{\alpha} \frac{1}{2} (|f_1 - g| + |f_2 - g|)$$

$$\geq \frac{1}{2} |f_1 - f_2| \geq \frac{1}{2} \text{diam } E(f, \epsilon) - \frac{\epsilon}{2}$$

$\epsilon \rightarrow 0$

Estimation of diam $E(f, \varepsilon)$.

Consider λ , "deconvolution parameter"

Proving
map

$$F_\lambda : P_d \rightarrow \mathbb{C}^{2d}$$

$$E^{(\lambda)}(f, \varepsilon) = F_\lambda^{-1}(B_\varepsilon(m))$$

$$m = \left[\sum_{j=1}^d c_j e^{it_j \cdot \lambda \cdot k} \right]_{k=0}^{2d-1}$$

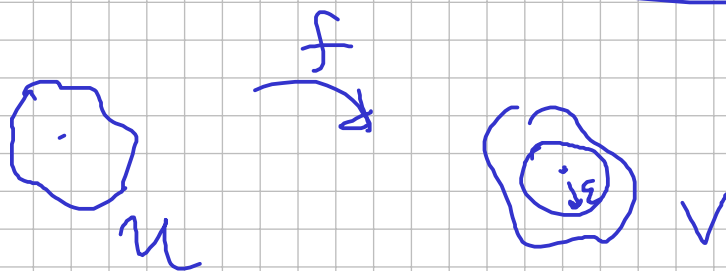
Easy to see that $\bigcap_{\lambda \in (0, \frac{\Omega}{2d-1})} E^{(\lambda)}(f, \varepsilon) \supseteq E(f, \varepsilon)$.

In particular, sufficient to estimate diam $E^{(\lambda)}(f, \varepsilon)$ for an "optimal" λ^* . (from above).

We've seen existence of $\lambda^* \asymp O(\Omega) \left| \frac{1}{\lambda} \left(\frac{1}{\lambda \Omega} \right)^{2p-2} \right|$

Additional ingredient: Inverse function theorem

Quantitative.



want to show existence of a large ball on which f^{-1} exists.

Classical IFT:

$f: B_1 \rightarrow B_2$, B_1, B_2 open, f holomorphic

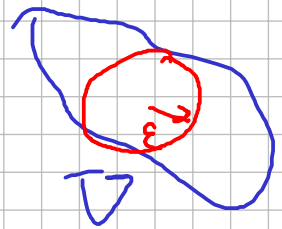
then $|J_f(z_0)| \neq 0$ iff $\exists U \subset B_1$
 $V \subset B_2$ open neighborhoods

such that $f: U \rightarrow V$ is biholomorphic
(f bijection, f^{-1} holomorphic).

Intuition:



\approx



Suppose $\|f^{-1}\| \leq A$

a ball of radius R will be mapped to a domain
of "radius" $\leq A \cdot \epsilon \leq R$

"safe" to take $\epsilon \approx \frac{R}{A}$.

How to find f^{-1} ?

Solve $y = f(x)$

$g(x) = y - f(x) = 0$

Newton's method

Can use but obtain
non-optimal bounds.

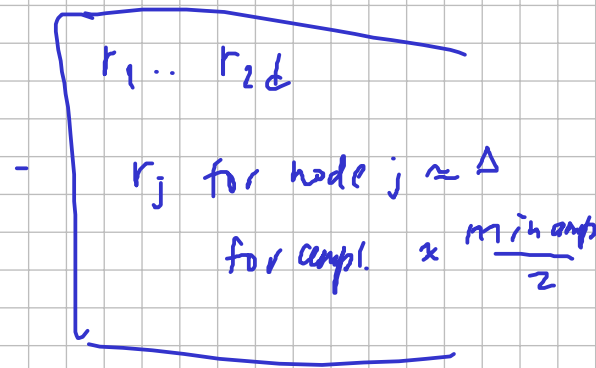
This $U \subset \mathbb{C}^n$ open, $\forall z \in U \quad |J_f(z)| \neq 0$

Further, suppose U contains a rectangle of side lengths

$$r = (r_1, \dots, r_n)$$

$$Q_r(a) = \{y: |y_i - a_i| \leq r_i\}$$

$a \in \mathbb{C}^n$.



Assume also that $\forall z \in Q_r(a)$

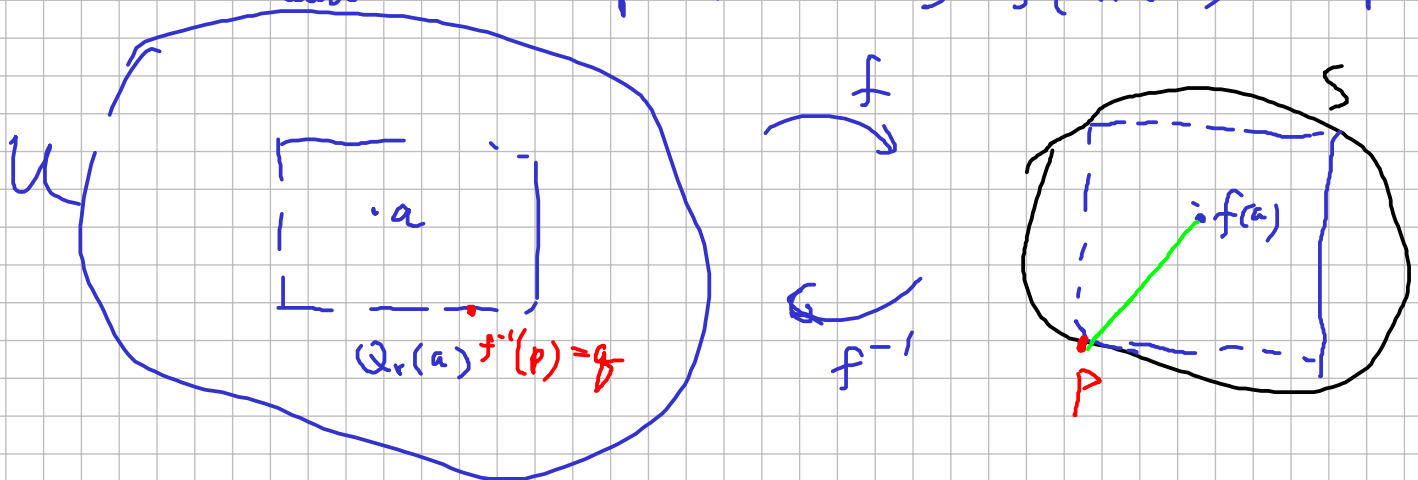
$$\sum_{j=1}^n |J_f^{-1}(z)|_{i,j} \leq A_i$$

Then $f(U)$ contains $Q_e = (e, \dots, e)$, where

$$e = \min \left(\frac{r_1}{A_1}, \dots, \frac{r_n}{A_n} \right).$$

Pf: f biholomorphism between U and V .
 and so homeomorphism

$$S = f(Q_r(a)) \rightarrow \text{compact}$$



Let \tilde{Q} be the maximal cube centered at $f(a)$, $\tilde{Q} \subset S$.

$$\Rightarrow \exists p \in \partial S \cap \partial \tilde{Q}, \quad f^{-1}(p) \in \partial Q_r(a)$$

$\tilde{Q} = Q_e$

$$\Rightarrow \exists j \text{ s.t. } |q_j - a_j| = r_j$$

Integrate f_j^{-1} from $f(a)$ to p .

Fundamental th. of calculus, mean value th.

$$r_j = \left| f_j^{-1}(f(a)) - f_j^{-1}(p) \right| = \left| \int_{f(a)}^p (Df_j^{-1})(y) dy \right|$$

$$\leq A_j \|p - f(a)\|$$

$$\Rightarrow \|p - f(a)\| \geq \frac{r_j}{A_j}$$



$$\left(\left| f^{-1}(a) - f^{-1}(b) \right| \right)_j \leq A_j \|a - b\|$$

$$a, b \in \mathbb{Q}_e$$

Back to clustered SR:



Th: for $\epsilon < \epsilon_{crit} \approx \left(\frac{1}{A_j} \right)^{2p_{max}-1}$

$$(min-max) \quad \mathcal{O}_j^{(t)} \leq A_j^{(t)} \cdot \epsilon$$

$$A_j^{(t)} = c \left(\frac{1}{\omega \Delta} \right)^{2p_j-2} \cdot \frac{1}{\sqrt{2}}$$

$$\frac{\Delta}{A_j} = \frac{r_j}{A_j}$$

[Note: $p_j=1$ we get "well-separated regime"]

Note: $\mathcal{U} = \{ m < |c_j| < M, |t_j - t_i| > \rho \text{ } i, j \text{ not in same cluster } d_i p_i \}$
 $c = c(p, n, \mu)$

Fact: can show matching lower bounds for $\mathcal{E}_j^{(t)}$
 Given \mathcal{U} , exhibit $f_1, f_2 \in \mathcal{U}$ $|(f_1)_j^{(t)} - (f_2)_j^{(t)}| \geq A_j^{(t)} \epsilon$
 and $\|\hat{f}_1 - \hat{f}_2\| \leq \epsilon$.

(divided differences, $f \sim \mathcal{J}_{\Delta}^{(p-1)}(t)$)

[also can do: given $f \in \mathcal{E}^d$, find f' s.t. ...]
 need lower bounds for F^{-1}

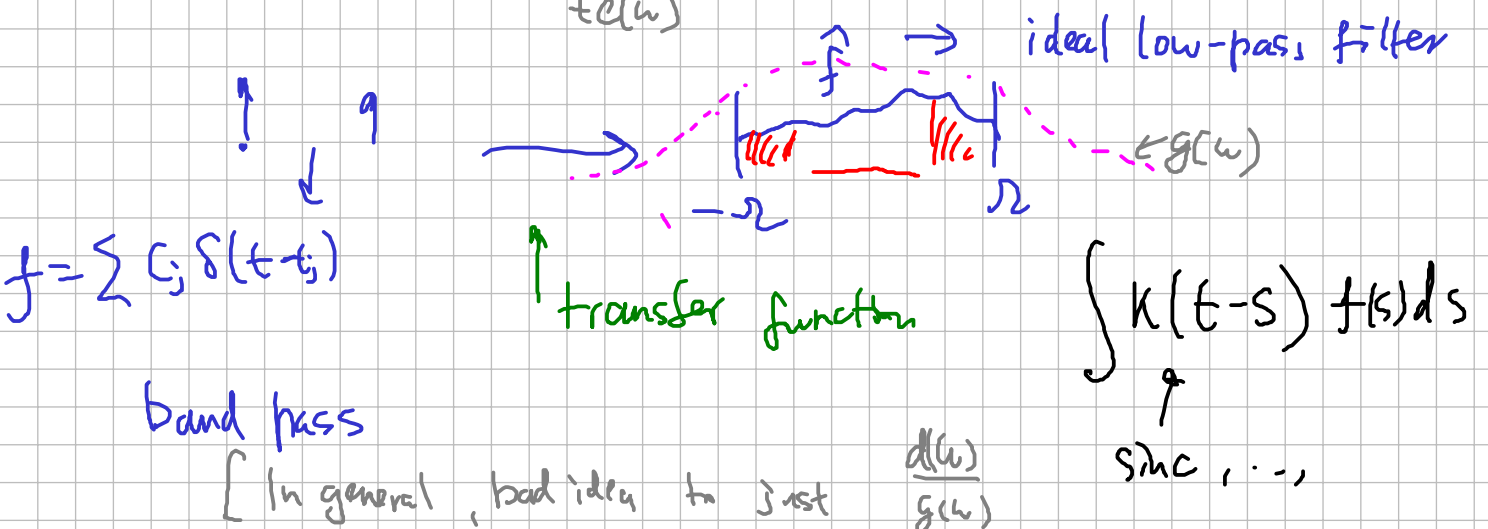
Open questions

1) Fine-tune inside \mathcal{U} , $c_j \in \mathbb{R}$ vs $c_j \in \mathbb{C}$,
 vs $c_j > 0$.

2) What exactly can we recover if $(\Omega \Delta)^{2p_{\max}-1} \in \mathcal{E} \subset (\Omega \Delta)^{2p'-1}$?
 - smaller clusters?
 - averages of big clusters?

3) $d \rightarrow \infty$, $p_{\max} \leq p$ need to find "local" algorithms

4) $d(\omega) = \left(\sum c_j e^{i\omega t_j} \right) g(\omega)$, for some classes of filters



(polynomial time)

Algorithms (tractable or less so...)

1) Try to find optimal x^* .

2) "Sparsity-type". discretize the point grid N pts $\{-\pi, \pi\}$

M. Elad $\nearrow c \in \mathbb{C}^N$, #nonzeros = d

R. Givyes

fat matrix

$$\rightarrow Fc = m + e$$

N measurements

$$\|c\|_0 \leq d$$

compressed sensing.

3) Least squares. (Gauss). data fitting
(nonlinear) Machine learning

$$\left(\int \dots \right)$$

Task: compute $\min_x f(x, \varepsilon)$ ε "nuisance parameters"

$$\text{s.t. } \begin{cases} g_i(x) \leq 0 \\ h_i(x) = 0 \end{cases}$$

$$x^*(\varepsilon) = \arg \min_x f(x, \varepsilon)$$

x - "primary".

L.S: $F(x) \rightarrow \begin{bmatrix} f_1 \\ \vdots \\ f_p \end{bmatrix}$, model

$$\left[f_k = \sum c_j e^{i\varepsilon_j k} \right]$$

for simplicity $d(\varepsilon) = \begin{bmatrix} d_1 \\ \vdots \\ d_p \end{bmatrix}$ data (noise ε)
(assume everything sufficiently smooth). $d(0) = F(x_0)$

$$f(x, \varepsilon) = \frac{1}{2} \|F(x) - d(\varepsilon)\|^2$$

Question: estimate $\|x^* - x_0\|$

Idea: consider $x^*(\varepsilon)$ as an implicit solution to

$$(\nabla_x f(x^*(\varepsilon), \varepsilon) \equiv 0). \quad \underbrace{\nabla_x f(x, \varepsilon)}_g = 0 \quad (*)$$

Can use implicit f-n theorem.

$$\nabla_x g \neq 0 \Rightarrow \nabla_{xx}^2 f(x_0, 0)$$

Minimum when $\nabla_{xx}^2 f(x_0, 0) \geq 0$. } sufficient conditions

$$\nabla_x f(x_0, 0) = 0$$

$$Dg \equiv 0$$

$$x'(\varepsilon) = -(\nabla_{xx}^2 f(x, \varepsilon))^{-1} \nabla_{x\varepsilon}^2 f(x, \varepsilon)$$

(can also do constrained min.)

For least squares: $J = \frac{\partial F}{\partial x}$

$$\nabla_x f = J^T (F - d)$$

$$\nabla_{xx}^2 f(x, 0) = J^T J$$

$$\nabla_{x\varepsilon}^2 f(x, \varepsilon) = -J^T d'(\varepsilon)$$

↑
perturbation
model

Simple case: $d' \approx \text{const}$ ($d \approx C_1 + C_2 \varepsilon$)

$$x'(0) = J^T d'(0)$$

Open questions:

1) Estimate $\|J^T\|_1$ in the multi-cluster setting

2) extend to finite ε .

3) Convergence speed, initialization. $x_{\text{init}} \approx x_0$

how close should this be?

(basin of attraction of the global optimum).